

# Nicolas Schischka

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✉ [nicolas-schischka](#)



## Education

<b>Master of Science Robotics, Cognition, Intelligence</b>	<i>Oct 2022 - Apr 2025</i>
◦ <b>Technical University of Munich</b> (Munich, Germany)	
◦ Dual study program in cooperation with the AUDI AG	
◦ GPA: 1.1 / 1.0	
◦ Master's Thesis: Leveraging Topology Estimation and Agent-Map Interaction for End-to-End Trajectory Forecasting (Grade: 1.0, Examiner: Dr. Federico Tombari)	
<b>Exchange Study Program Computer Science</b>	<i>Sept 2023 - Dec 2023</i>
◦ <b>Concordia University</b> (Montréal, Canada)	
◦ GPA: 4.30 / 4.30	
<b>Bachelor of Science Mechanical Engineering</b>	<i>Oct 2018 - Apr 2022</i>
◦ <b>Technical University of Munich</b> (Munich, Germany)	
◦ GPA: 1.5 / 1.0 (Top 2.5 %)	
◦ Bachelor's Thesis: Artificial Intelligence in the Material Development of Composites (Grade: 1.0, Examiner: Prof. Dr.-Ing. Klaus Drechsler)	
<b>Abitur</b> (equivalent to A-Levels in the UK)	<i>Sep 2010 - Jun 2018</i>
◦ <b>Gymnasium Gröbenzell</b> (Gröbenzell, Germany)	
◦ GPA: 1.2 / 1.0	

## Professional Experience

<b>Research Assistant</b> <i>Robot Learning Lab, University of Freiburg</i>	<i>July 2025 - today</i> <i>Freiburg, DE</i>
◦ Conduct of research in the area of perception for autonomous driving	
◦ Research about collective perception	
<b>Master's Thesis &amp; Research Intern Pre-Development Perception</b> <i>CARIAD SE</i>	<i>July 2024 - March 2025</i> <i>Munich, DE</i>
◦ Research intern in the development of an end-to-end model for motion forecasting based on multi-view images in MMCV	
◦ Fusion of a sparse 3D detection model with an online map generation model	
<b>Intern Autonomous Driving</b> <i>Audi of America, Inc.</i>	<i>Apr 2024 - July 2024</i> <i>San Jose, CA, US</i>
◦ Support of the concept car team to develop an autonomous vehicle	
◦ Further development of autonomous driving functions (PID controller and extended Kalman filter) in C++/ROS	
<b>Research Intern Development Innovation</b> <i>AUDI AG</i>	<i>Mar 2024 - Apr 2024</i> <i>Ingolstadt, DE</i>
◦ Collaboration in a research project related to formal methods in the context of path planning for autonomous driving	
◦ Development of a path planner based on Signal Temporal Logic (STL)	
<b>Intern Development of Vehicle Data Analytics / Artificial Intelligence</b> <i>AUDI AG</i>	<i>Jan 2024 - Feb 2024</i> <i>Ingolstadt, DE</i>
◦ Pre-processing of vehicle sensor data in Dataiku	
◦ Application of a time series classification model for driver identification in PyTorch	

**Intern Project Control MEB, PPE41, e-tron**  
*AUDI AG*

*Mar 2023 - Apr 2023*  
*Ingolstadt, DE*

- Improvement of reporting for cross-series topics
- Information procurement and processing on model series and equipment packages

**Intern Virtual Development of Vehicle Dynamics**  
*BMW AG*

*Apr 2021 - Sep 2021*  
*Munich, DE*

- Further development of a two-track model in Simulink
- Implementation of vehicle dynamics simulations in Matlab/Simulink
- Development of tests for software products using modern tools

**Teaching Assistant**

*Technical University of Munich*

*Nov 2019 - Feb 2021*  
*Munich, DE*

- Tutorial of Engineering Mechanics 1 in the winter semester 2019/20 and 2020/21
- Tutorial of Engineering Mechanics 2 in the summer semester 2020

## Publications

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### Peer-Reviewed Publications

- [1] **N. Schischka\***, H. Schieber\*, M. A. Karaoglu\*, M. Gorgulu, F. Grötzner, A. Ladikos, N. Navab, D. Roth, and B. Busam, "DynaMoN: Motion-Aware Fast and Robust Camera Localization for Dynamic Neural Radiance Fields," *IEEE Robotics and Automation Letters*, vol. 10, no. 1, pp. 548-555, Jan. 2025.
- [2] A. Dhonthi, **N. Schischka**, E. M. Hahn, and V. Hashemi, "Autonomous Vehicles Path Planning under Temporal Logic Specifications," in *Formal Methods: Foundations and Applications*, S. C. Nogueira and C. Teodorov, Eds., Lecture Notes in Computer Science, vol. 15403, Cham: Springer, 2025, pp. 35–45.

### Abstract/Non-Peer-Reviewed Publications

- [1] A. Seidel, **N. Schischka**, D. Bublitz, and K. Drechsler, "Prediction of Elastic Properties of Unidirectional Fibre-Reinforced Polymers Using Image Processing of Micrographs, Microscale Finite Element Simulations and Feedforward Neural Networks," (Abstract) In *1st Conference on Artificial Intelligence in Materials Science and Engineering (AIMSE)*, Saarbrücken, Germany, 2023.

## Reviewing

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- IEEE International Conference on Robotics & Automation (ICRA) [2025, 2026]  
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) [2025]  
IEEE Robotics and Automation Letters (RA-L) [2025]

## Awards

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**GDCh-Award** for the best A-level student in chemistry

**Deutschlandstipendium** (Oct 2019 - Sep 2020)

## Hobbies

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Landscape photography, boardgames, listening to music, hiking, concerts, football

## Proficiencies and Skill

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**Programming knowledge:** Python, C, C++, git, PyTorch, NumPy, Matplotlib, MMCV, ROS, Docker

**Software proficiencies:** Microsoft Office, Atlassian products (Bitbucket, Confluence, Jira), Autodesk Inventor, DS Catia V5, L<sup>A</sup>T<sub>E</sub>X, Dataiku, Microsoft Azure

**Language proficiencies:** German (native), English (C1), Spanish (A2), French (A1)